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SYSTEM OF DYNAMIC PULSE POSITION TRACKS FOR PULSE-LIKE EXCITATION IN SPEECH CODING

INVENTOR

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BACKGROUND OF THE INVENTION

1. Cross Reference to Related Applications.

The present application claims the benefit of U.S. Provisional Application No. 60/233,045, filed September 15, 2000, which is incorporated by reference herein.

The following co-pending and commonly assigned U.S. patent applications were filed on the same day as the above-referenced Provisional Application. All of these applications relate to and further describe other aspects of the embodiments disclosed in this application and are incorporated by reference in their entirety.

| United States Patent Application Serial Number, |
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| "SELECTABLE MODE VOCODER SYSTEM," Attorney Reference Number: |
| 98RSS365CIP (10508.4), filed on September 15, 2000, and is now United States |
| Patent Number |
| United States Patent Application Serial Number, "INJECTING |
| HIGH FREQUENCY NOISE INTO PULSE EXCITATION FOR LOW BIT RATE |
| CELP," Attorney Reference Number: 00CXT0065D (10508.5), filed on September |
| 15, 2000, and is now United States Patent Number |
| United States Patent Application Serial Number, "SHORT |
| TERM ENHANCEMENT IN CELP SPEECH CODING," Attorney Reference |
| Number: 00CXT0666N (10508.6), filed on September 15, 2000, and is now United |
| States Patent Number |
| United States Patent Application Serial Number, "SPEECH |
| CODING SYSTEM WITH TIME-DOMAIN NOISE ATTENUATION," Attorney |

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Reference Number: 00CXT0554N (10508.8), filed on September 15, 2000, and is now United States Patent Number United States Patent Application Serial Number , "SYSTEM FOR AN ADAPTIVE EXCITATION PATTERN FOR SPEECH CODING," Attorney Reference Number: 98RSS366 (10508.9), filed on September 15, 2000, and is now United States Patent Number United States Patent Application Serial Number , "SYSTEM FOR ENCODING SPEECH INFORMATION USING AN ADAPTIVE CODEBOOK WITH DIFFERENT RESOLUTION LEVELS," Attorney Reference Number: 00CXT0670N (10508.13), filed on September 15, 2000, and is now United States Patent Number . United States Patent Application Serial Number , "CODEBOOK TABLES FOR ENCODING AND DECODING," Attorney Reference Number: 00CXT0669N (10508.14), filed on September 15, 2000, and is now United States Patent Number United States Patent Application Serial Number , "BIT STREAM PROTOCOL FOR TRANSMISSION OF ENCODED VOICE SIGNALS." Attorney Reference Number: 00CXT0668N (10508.15), filed on September 15, 2000, and is now United States Patent Number United States Patent Application Serial Number FOR FILTERING SPECTRAL CONTENT OF A SIGNAL FOR SPEECH ENCODING," Attorney Reference Number: 00CXT0667N (10508.16), filed on September 15, 2000, and is now United States Patent Number . United States Patent Application Serial Number ______, "SYSTEM FOR ENCODING AND DECODING SPEECH SIGNALS," Attorney Reference Number: 00CXT0665N (10508.17), filed on September 15, 2000, and is now United States Patent Number United States Patent Application Serial Number , "SYSTEM FOR SPEECH ENCODING HAVING AN ADAPTIVE FRAME ARRANGEMENT," Attorney Reference Number: 98RSS384CIP (10508.18), filed on September 15, 2000, and is now United States Patent Number

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FOR IMPROVED USE OF PITCH ENHANCEMENT WITH SUBCODEBOOKS," Attorney Reference Number: 00CXT0569N (10508.19), filed on September 15, 2000, and is now United States Patent Number ______.

United States Patent Application Serial Number

2. Technical Field.

This invention relates to speech communication systems and, more particularly, to systems for digital speech coding.

3. Related Art.

One prevalent mode of human communication is by the use of communication systems. Communication systems include both wireline and wireless radio systems. Data and voice transmissions within a wireless system occur within a bandwidth of an allowed frequency range. Due to increased wireless telecommunication traffic, reduced bandwidth of transmissions to improve capacity with the system is desirable.

Voice and data are transmitted digitally in wireless communications due to noise immunity, reliability, compactness of equipment, and the ability to implement sophisticated signal processing functions using digital techniques. One form of digital transmission is accomplished using digital speech processing systems. Waveforms representing analog speech signals are sampled and then digitally encoded. The number of bits of the encoded signal can be expressed as a bit rate that specifies the number of bits to describe one second of speech. Over the years, significant variations and enhancements have been applied to waveform matching techniques in an effort to improve the quality of the synthesized speech and increase the speech compression.

A reduction in the quality of the synthesized (or reconstructed) speech may occur with respect to the original speech. This divergence in the quality of the synthesized speech is due in part to the failure to closely replicate perceptual aspects of the original speech with the bits of data available to describe the signal. Poor replication of the perceptual aspects could result in noise, loss of clarity, and the failure to capture recognizable characteristics such as tone, pitch and magnitude. These characteristics allow a listener to recognize who the speaker is, as well as

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providing other perception based features, such as, intelligibility and naturalness of the speech.

Accordingly, there is a need for systems of speech coding that are capable of minimizing the bandwidth of original speech, while providing synthesized speech that closely resembles the original speech and captures the perceptually important features of the speech.

SUMMARY

In many communication systems, an original speech signal is digitized to create a digital speech signal. The digital speech signal may pass through long-term and short-term filters to create a digital excitation signal. The digital excitation signal represents an ideal excitation signal in the form of pulses. The pulses are defined at positions and the positions are divided among tracks to reduce bandwidth. The pulses are encoded at an encoder. The encoded information is sent via a communication link to a decoder to be decoded. The decoded signals represent synthesized speech that is an approximation the original speech signal. Embodiments disclosed include systems for dynamically coding pulses that represent an excitation signal.

A track or set of tracks that define possible pulse positions are determined based on available information sent to a decoder. The available information is used to determine a track that is likely to define pulse positions at or near pulse signals with high energy, i.e., pulse signals that are likely to contain information that is important for speech processing purposes. As an alternative, at least one first track may include fixed pulse positions, and the remaining tracks may include pulse positions that can change according to the position of a coded pulse in the first track. Another alternative may include dynamically arranging all tracks according to pulse positions that are arranged according to a reference position that is likely to produce a high-energy pulse signal. The reference position can be found from a past excitation signal.

Other systems, methods, features and advantages of the invention will be or will become apparent to one with skill in the art upon examination of the following figures and detailed description. It is intended that all such additional systems,

methods, features and advantages be included within this description, be within the scope of the invention, and be protected by the accompanying claims.

BRIEF DESCRIPTION OF THE FIGURES

The components in the figures are not necessarily to scale, emphasis instead being placed upon illustrating the principles of the invention. Moreover, in the figures, like reference numerals designate corresponding parts throughout the different views.

Fig. 1 is a block diagram illustrating an exemplary system that utilizes dynamic pulse track positions of the disclosed embodiments to enhance the quality of the coded pulse data.

Fig. 2 is a diagram of an exemplary system that uses tracks to code the signals at a low bit rate.

Fig. 3 is a block diagram illustrating an exemplary inverse-filtering system.

Fig. 4 is a block diagram illustrating a portion of an exemplary coder.

Fig. 5 illustrates an exemplary speech signal and processed signals obtained from the speech signal by removing a short-term LPC correlation and long-term correlation. Fig. 6 is a block diagram illustrating an algorithm that assigns a track or set of tracks based on available information, such as a selected signal type.

Fig. 7 is a diagram that describes an embodiment of dynamic track allocation in which at least one track includes fixed pulse positions and the remaining tracks include dynamically allocated pulse positions.

Fig. 8 is a diagram that describes an embodiment of dynamic track allocation in which the algorithm dynamically allocates all pulse positions for all of the tracks.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

A system is provided that utilizes dynamic pulse track positions to enhance coded data that, when decoded, produces a synthesized speech signal that resembles an original speech sample. The system typically is used to enhance speech signals transmitted via a wireless communications network. Mobile cellular standards, such as the Adaptive Multi-Rate (AMR) and Selectable Mode Vocoder (SMV) standards,

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utilized to describe the invention, however, those skilled in the art will appreciate that other systems could be used with the invention, such as AMR. Operation of the SMV system is described in commonly assigned U.S. Patent App., "SYSTEM OF ENCODING AND DECODING SPEECH SIGNALS," by Yang Gao, Adil Beyassine, Jes Thyssen, Eyal Shlomot and Huan-Yu Su, previously incorporated by reference. Fig. 1 is a block diagram illustrating an exemplary system 100 that utilizes

define digital transmission in wireless communication systems. An SMV system is

dynamic pulse track positions of the disclosed embodiments to enhance the quality of the coded pulse data. The system 100 includes an encoder 120, a decoder 130 and a communications link 140. In one embodiment, the system includes excitation processing circuitry 110 to dynamically allocate tracks (described in Fig. 2) based on available information, such as signal type information. The SMV system uses type zero to code non-periodic signals and type one to code periodic-like signals. Other types of information could be used such as codebook (described in Fig. 4) and pitch (described in Fig. 5) information. The signal type or other information is sent from the encoder 120 to the decoder 130 via the communications link 140. communications link 140 is any communication media capable of transmitting voiced data, including but not limited to, wireless communication media, wireline communication media, fiber-optic communication media, and Ethernet. The encoder 120 and decoder 130 may be implemented on one or more integrated circuits (IC), such as a codec (coder/decoder), digital signal processor (DSP) or general processors.

The encoder 120 receives input speech and codes the input speech with coding circuitry 160 to form a coded excitation signal. To reduce the amount of data to be transferred over the communications link 140, the encoder includes a codebook 165 that contains a matrix of values that are used to represent the coded excitation signal. The decoder 130 also includes the codebook 165. To reduce the amount of data sent over the communications link 140, only vector information describing the location of the representative value in the matrix is sent to the decoder, instead of the actual value. The decoder includes decoding circuitry 170 to decode the coded data sent from the encoder 120, to produce synthesized speech 180 that is representative of the input speech 150.

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Fig. 2 is a diagram of an exemplary system that uses tracks to code the signals at a low bit rate. In this example, the signal 200 is represented by twelve positions per sub-frame divided between one or more tracks, for example, track 1, track 2 and track 3. More or less pulse positions could be used per sub-frame, such as the forty positions used in the typical SMV system, and the positions can be distributed among more or less tracks. In an ACELP design, tracks are utilized to reduce the possible positions per track for each pulse and thus reduce the amount of bits necessary to represent the pulse.

For example, track 1 includes positions {1, 4, 7, and 10}, track 2 includes positions {2, 5, 8, and 11}, and track 3 includes positions {3, 6, 9, and 12}. Other arrangements of positions per track may be used. In this manner, a pulse is limited to the four possible positions per track. For each track, two bits can be used to code the four possible positions of the pulses, and a sign bit is used to code the magnitude of the pulses, either positive or negative. Thus, only nine bits are needed to code the three pulses for twelve possible positions.

An algorithm is used to determine the position of the pulse per track. An exemplary algorithm is described in a commonly assigned U.S. Pat. App. entitled "COMPLETED FIXED CODEBOOK FOR SPEECH CODER," Serial No. 09/156,814, filed September 18, 1998, and is incorporated by reference. Typically, the position is determined according to the pulse having the best closed-loop waveform matching for the possible positions. For example, track 1 includes possible positions {1, 4, 7, and 10}, and the pulse with the best closed-loop waveform matching is located at position 7, thus the algorithm codes the pulse located at position seven (see Fig. 2). In a similar manner, the algorithm codes a pulse located at position 11 for track 2 and codes a pulse located at position 3 for track 3. Thus, three pulses are coded to generate a synthesized excitation that approximately describes the signal for a particular sub-frame.

Figs. 3 and 4 are block diagrams illustrating a portion of an exemplary encoder 300 and decoder 400, respectively. The portion of the encoder 300 includes a linear prediction coding (LPC) filter A(z) 310 that converts input speech s(n) 320 to an LPC residual signal e(n) 330 (discussed in Fig. 5). The decoder 400 in Fig. 4 includes an

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Fig. 5 illustrates an exemplary speech signal and processed signals obtained from the speech signal by removing a short-term LPC correlation and long-term correlation. Exemplary methods of LPC include Code Excited Linear Prediction (CELP), eXtended CELP (eX-CELP), and algebraic CELP (ACELP). LPC coding may be a frame-based algorithm that stores sampled input speech signals 500 into blocks of samples called sub-frames 510. An exemplary SMV system operates at a frame size of twenty milliseconds (ms) or one hundred sixty samples per frame. Other sized frames may be used. For signal processing purposes, the frames are divided into sub-frames 510 that are typically forty samples in size. LPC coding represents a given value of input speech 500 using previously measured values. Speech s at an instant n can be approximated by:

$$s(n) \approx a_1 s(n-1) + a_2 s(n-2) + \dots + a_n s(n-p)$$
 (Equation 1)

where a_1 , a_2 , \cdots a_p are LPC coefficients and p is the LPC order. As stated, Equation 1 is only an approximation of speech s, thus, the difference between the input speech sample and the predicted speech sample is the excitation signal e(n), or a LPC residual 520. The LPC residual 520 can be expressed as:

$$e(n) = s(n) - a_1 s(n-1) - a_2 s(n-2) - \dots - a_n s(n-n)$$
 (Equation 2)

The LPC residual 520 has a level of periodicity similar to the speech signal s(n). The approximately periodic part of the LPC residual 520 is referred to as pitch cycle, where lag L is a measure of the pitch delay in samples. The general shape of the LPC residual 520 is periodic-like for voiced speech and evolves relatively slowly as a function of time, facilitating long-term pitch prediction of the LPC residual 520. Long-term pitch predication is used to determine a pitch residual signal r(n), or pitch residual 530. Pitch residual 530 is defined as the difference between the LPC residual 520 and a pitch prediction contribution, which is expressed as:

$$r(n) = e(n) - \beta e(n - \text{Lag})$$
 (Equation 3)

where β is a pitch prediction coefficient and $\beta e(n\text{-Lag})$ is the pitch prediction contribution.

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Fig. 4 shows, for signal processing purposes, the LPC residual e(n) is processed into the pitch residual signal r(n) and the pitch prediction contribution $\beta e(n-\text{Lag})$. The pitch residual signal r(n) is coded with a fixed codebook 430 and the pitch prediction contribution $\beta e(n-\text{Lag})$ is coded with an adaptive codebook 440. The fixed codebook could include sub-codebooks, e.g., sub-codebook one 432, sub-codebook two 434 and sub-codebook three 436, for coding periodic speech-like signals, non-periodic pulse-like signals and random signals, respectively. Any of the sub-codebooks 432, 434 and 436 can use the dynamic tracks and different types of dynamic tracks could be applied according to signal type, as explained in more detail with regard to Fig. 6.

Fig. 6 is a block diagram illustrating an algorithm that assigns a track or set of tracks based on available information, such as a selected signal type. Information, other than signal type information, could be used such as codebook (adaptive or fixed) information, pitch information and previously coded pulse information (such as pulse position information). In this embodiment, the pulse positions of tracks 1-3 are fixed for a specific sub-frame, but the tracks used to code each pulse can vary. The tracks can vary from one sub-frame to the next sub-frame to better represent changes to the available information. In block 610, a signal type is determined from information available to the decoder 130 (Fig. 1). The signal type is chosen, for example, according to the signal being processed, e.g., whether or not the signal is a periodic-like signal. A track or set of tracks to code the pulsed signal is assigned as a function of the signal type information. In block 620, if type zero is utilized, a first track or set of tracks with set positions is used to code the pulses, and, in block 630, if type one is utilized, another track or set of tracks with fixed positions is selected to code the pulse.

Defining the positions for each track dynamically may be implementation dependent. For example, some tracks include more positions than other tracks, and multiple tracks could include the same position. Also, some tracks could include positions defined towards the beginning of the sub-frame and some tracks could include positions defined towards the middle or end on the sub-frame. For example, track 1 could include positions {1, 2, 3, 4, 5 and 6}, track 2 could include positions {7 and 8} and track 3 could include positions {8, 9, 10, 11 and 12}. A track preferably is

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Fig. 7 is a diagram that describes an embodiment of dynamic track allocation in which at least one track includes fixed pulse positions and the remaining tracks include dynamically allocated pulse positions. In block 710, for each sub-frame a known algorithm may be used to determine the position of a first pulse in the fixed track with fixed pulse candidate positions, e.g., track 1. An exemplary algorithm is described in a commonly assigned U.S. Pat. App. entitled "COMPLETED FIXED CODEBOOK FOR SPEECH CODER," Serial No. 09/156,814, filed September 18, 1998, and is incorporated by reference. In block 720, when the pulse is positioned in track 1, pulse positions are determined for the next track, e.g., track 2. Pulse positions for track 2 may be dynamically constructed based on the coded position of the first pulse in the track 1. In block 730, the locations of the remaining pulses, e.g., third pulse, are determined for the remaining tracks, e.g., track 3, using the dynamically allocated track positions.

The dynamic process accounts for speech signal characteristics. When analyzing the pitch residual signal r(n) and other periodic-like signals, there is a high possibility that significant pulses, i.e., having a high magnitude, are located around the first pulse. By coding the first pulse position and then dynamically specifying candidate pulse positions relative to the first pulse position, the algorithm can allocate more candidate track positions to find the first pulse. The total amount of allocated pulse positions per track is implementation dependent and depends on the amount of bits allowed to define the positions. For example, track 1 includes pulse positions $\{1, 5, 10, 15, 20 \text{ and } 25\}$. If the first pulse is determined at position 10 of track 1, the positions at track 2 are defined at $\{10-x, 10-y, 10+y \text{ and } 10+x\}$, or $\{6, 8, 12 \text{ and } 14\}$ if x equals four and y equals two. Likewise, the algorithm may define the pulse positions of track 3 at $\{10-a, 10-b, 10+b \text{ and } 10+a\}$, or $\{7, 9, 11 \text{ and } 13\}$ if a equals three and b equals one. Other arrangements are possible.

Fig. 8 is a diagram that describes an embodiment of dynamic track allocation in which the algorithm dynamically allocates all pulse positions for all of the tracks, e.g., track 1, track 2 and track 3. The pitch lag L (Fig. 5) and the pitch coefficient β

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In block 820, the algorithm of the present embodiment uses information of the pitch prediction contribution $\beta e(n\text{-Lag})$ to derive an estimation of positions of main peaks from past excitation signals e(n). Because the position of the main peak previously has been coded in the adaptive codebook 440, the derivation of the position of the main peak may occur at either the encoder 120 or the decoder 130 without introducing additional bits into the communication link 140 (Fig. 1). The main peaks are determined using an algorithm. For example, an energy measure algorithm known to those skilled in the art searches all positions of the pitch prediction contribution $\beta e(n\text{-Lag})$ coded in the adaptive codebook 440 for the position with a peak having the highest energy. In this manner, the discovered main peak location is likely to contain useful information to determine tracks.

In block 830, when the algorithm determines a position of the main peak, the algorithm dynamically constructs candidate pulse positions for each track, e.g., track 1, track 2 and track 3, based on the derived positions of the main peaks. In this manner, if the main peak from a past sub-frame is derived at position 10, track 1 of the current sub-frame is preferably defined as including pulse positions at and around position 10. Different dynamic tracks may be based on different main peak locations. When the first main peak is estimated, an estimate of a second main peak preferably excludes the first peak. In this manner, the pulse positions for track 2 are defined at and around the location of the second main peak for the current sub-frame.

While various embodiments of the invention have been described, it will be apparent to those of ordinary skill in the art that many more embodiments and implementations are possible that are within the scope of this invention. Accordingly, the invention is not to be restricted except in light of the attached claims and their equivalents.